Short Course for PhD Students (Barcelona, September 5-12, 2019)

Recent Results on Planar and Spherical Kinematics

Raffaele Di Gregorio

This short course illustrates recent results, the speaker deduced, on planar and spherical kinematics, together with their use in planar dynamics.

1st Lecture (3 hours on September 5, 2019)

Planar Kinematics Revisited through Instant Centers (ICs)

- Role of the ICs in planar mechanism design (e.g., vehicle suspensions, lower-limb prostheses for amputees, etc.)
- Systematic determination of all the ICs: the case of the indeterminate linkages

- Singularity analysis with the ICs: single-DOF and multi-DOF mechanisms

2nd Lecture (3 hours on September ??, 2019)

Extension to Spherical Kinematics by Using Instantaneous Pole Axes (IPAs)

- From planar to spherical geometry: notations
- Systematic determination of all the IPAs
- Singularity analysis of spherical mechanisms with the IPAs

3rd Lecture (3 hours on September 12, 2019)

Dynamics of Planar Mechanisms

- Dynamic models of single-DOF planar mechanisms based on centrodes and velocity coefficients
- Mechanics of planar mechanisms in the configuration space

References

- Di Gregorio R., 2007, "A novel geometric and analytic technique for the singularity analysis of one-dof planar mechanisms," *Mechanism and Machine Theory*, 42(11):1462-1483
- Di Gregorio R., 2008, "An Algorithm for Analytically Calculating the Positions of the Secondary Instant Centers of Indeterminate Linkages," *ASME J. Mechanical Design*, 130(4):042303-042303-9
- Di Gregorio R., 2009, "A novel method for the singularity analysis of planar mechanisms with more than one degree of freedom," *Mechanism and Machine Theory*, 44(1):83–102
- Simionescu P.A., Talpasanu I., Di Gregorio R., 2010, "Instant-Center Based Force Transmissivity and Singularity Analysis of Planar Linkages," *ASME J. Mechanisms and Robotics*, 2(2):021011 (12 pages)
- Di Gregorio R., 2011, "A general algorithm for analytically determining all the instantaneous pole axis locations in single-DOF spherical mechanisms," *Proc. IMechE Part C: J. Mechanical Engineering Science*, 225(9): 2062-2075
- Di Gregorio R., 2013, "Analytical method for the singularity analysis and exhaustive enumeration of the singularity conditions in single-degree-of-freedom spherical mechanisms," *Proc. IMechE Part C: J. Mechanical Engineering Science*, 227(8) 1830–1840
- Di Gregorio R., 2015, "Analytic and Geometric Technique for the Singularity Analysis of Multi-Degreeof-Freedom Spherical Mechanisms," *ASME J. Mechanisms and Robotics*, 7(3): 031008 (9 pages)
- Di Gregorio R., 2016, "A Novel Dynamic Model for Single Degree-of-Freedom Planar Mechanisms Based on Instant Centers," *ASME J. Mechanisms and Robotics*, 8(1):011013 (8 pages)
- Di Gregorio R., 2015, "Kinematics and dynamics of planar mechanisms reinterpreted in rigid-body's configuration space," *Meccanica*, 51(4):993–1005. doi:10.1007/s11012-015-0251-8
- Di Gregorio R., 2019, "On the Use of Instant Centers to Build Dynamic Models of Single-dof Planar Mechanisms," In: Lenarcic J., Parenti-Castelli V. (eds) Advances in Robot Kinematics 2018. ARK 2018. Springer Proceedings in Advanced Robotics, vol 8, pp. 242-249, Springer, Cham