

# PlanCollabNL: Leveraging Large Language Models for Adaptive Plan Generation in Human-Robot Collaboration

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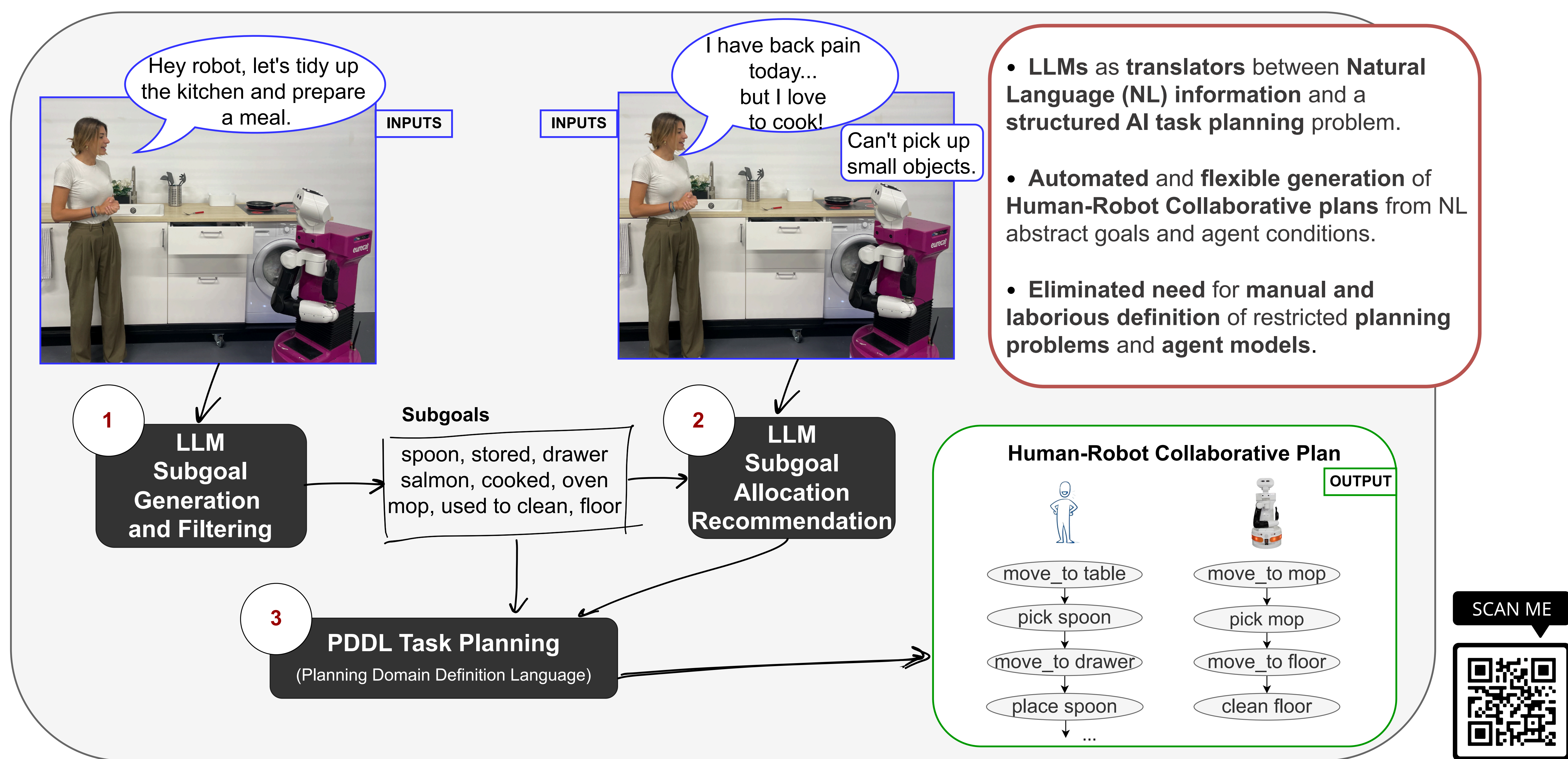
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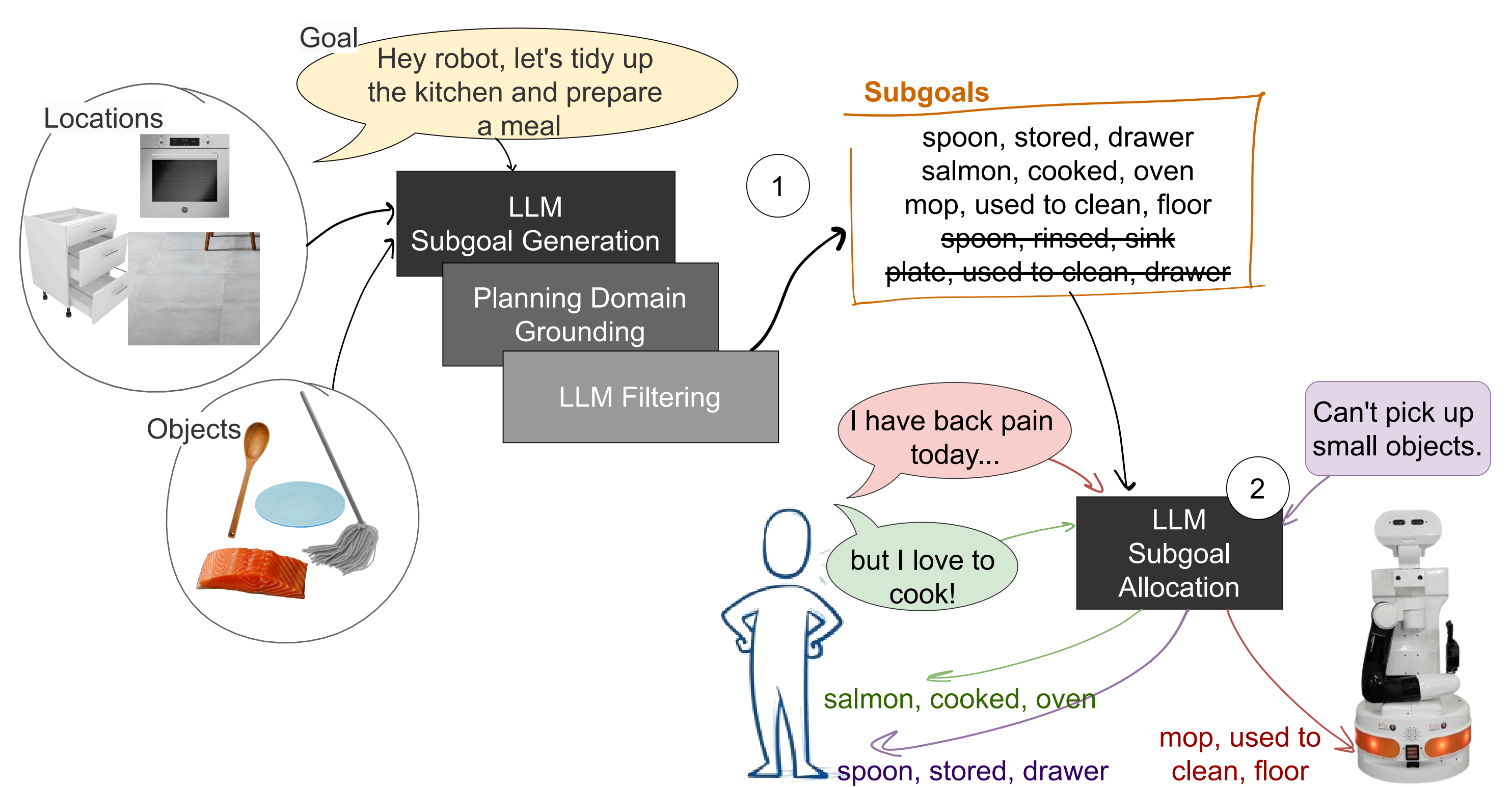
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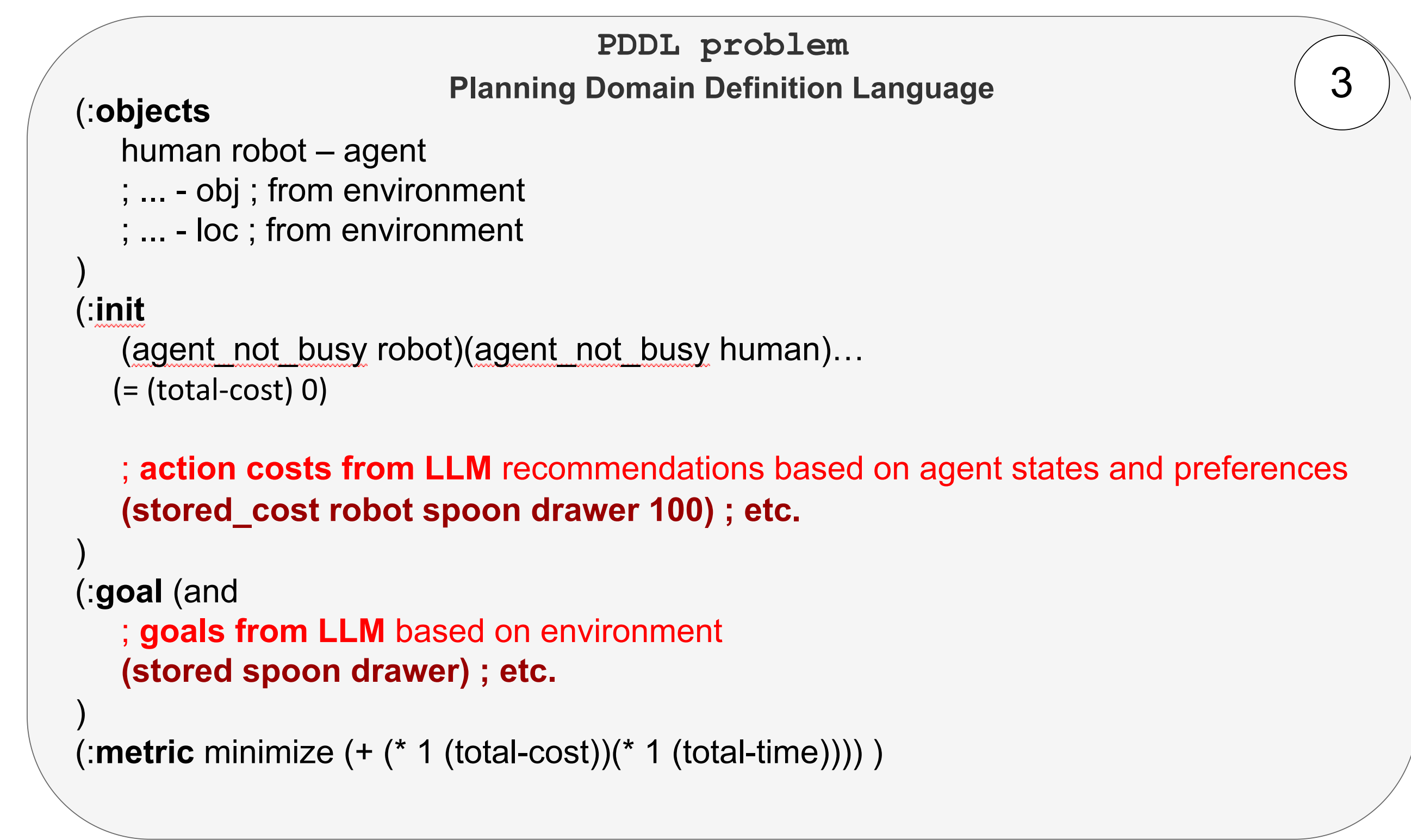
## Human-Robot Collaborative Plan Generation from a Natural Language Goal and Agent Conditions



### LLM-based 1) Subgoal Generation and 2) Allocation



### 3) From NL to Structured Planning Language



## Results

