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RESEARCH INTERESTS

Computer Vision: Shape and motion recovery; Object detection and recognition; Rigid and deformable 3D tracking; Feature extraction. Application of these topics to robotics, medical imaging and computer graphics.

PROFESSIONAL EXPERIENCE

2008-present Associate Researcher, Institut de Robòtica i Informàtica Industrial
Spanish National Research Council - Universitat Politècnica de Catalunya
2007-2008 Postdoctoral Researcher, Computer Vision Laboratory
Ecole Polytechnique Fédérale de Lausanne, Switzerland
2005-2006 Postdoctoral Researcher, Computer Vision Laboratory
Columbia University, USA
2004-2005 Visiting Scientist, Laboratory for the Study of Visual Appearance
Columbia University, USA
2001-2005 PhD Student, Institut de Robòtica i Informàtica Industrial
Spanish National Research Council - Universitat Politècnica de Catalunya

EDUCATIONAL BACKGROUND

11/2005 PhD in Computer Science, Universitat Politècnica de Catalunya
08/2002 M.S. in Electronic Engineering, Universitat de Barcelona
03/2001 M.S. in Industrial Engineering, Universitat Politècnica de Catalunya

AWARDS

2017 Best Paper Award
ICCV Computer Vision For Fashion Workshop, Venice, Italy.
2017 E.Simo-Serra (under my supervision) received the PhD Thesis Extraordinary Award.
2017 Google Faculty Research Award.
2016 E.Simo-Serra PhD Thesis (under my supervision) received the
Marc Esteve Award of the Catalan Association of Artificial Intelligence.
2015 Diploma of the Universitat Politècnica de Catalunya
In Recognition to the Best Paper Award at Jornadas de Automàtica 2014 and to the Best
Reviewer Award at CVPR 2014.
2015 Best Poster Award
Iberian Conf. on Pattern Recogn. and Image Analysis (IBPRIA), Santiago Compost., Spain.
2015 Best Paper Award
International Conference on Machine Vision Applications, Tokyo, Japan.
2014 Best Computer Vision Paper Award
Jornadas Automàtica, Valencia, Spain.
2014 Outstanding Reviewer Award
Conference on Computer Vision and Pattern Recognition (CVPR), Columbus, USA.

2012	Outstanding Reviewer Award European Conference on Computer Vision (ECCV), Florence, Italy.
2009	Nomination to Best Paper Award Int. Conference on Intelligent Robots and Systems (IROS), Saint Louis, USA.
2008	PhD Extraordinary Award Universitat Politècnica de Catalunya.
2005	Best Paper Award Iberian Conf. on Pattern Recogn. and Image Analysis (IBPRIA), Estoril, Portugal.

PARTICIPATION IN RESEARCH PROJECTS

Ongoing projects

- **Principal Investigator** of the National project HuMoUR “Markerless 3D Human Motion Understanding for Adaptive Robot Behavior” (166 K€), 2018–2020.
- **Co-investigator** of the European project AEROARMS “Aerial Robotics System Integrating Multiple Arms and Advanced Manipulation Capabilities for Inspection and Maintenance” (563 K€), 2015–2019.
- **Co-investigator** of the ERA-Net Chistera project “IDRESS - Assistive Interactive Robotic System for Support in Dressing” (140 K€), 2015–2018.

Finished projects

- **Principal Investigator** (with V. Lepetit) of the Google Faculty Research Award project “Geometry-aware CNNs for Non-Rigid Shape Reconstruction” (46.5 K\$), 2017-2018.
- **Principal Investigator** of the National project RobInstruct “Instructing robots using natural communication skills” (160 K€), 2015–2017.
- **Principal Investigator**, Programme “Acciones de Dinamización de Carácter Internacional Europa Investigación”, for the project “Automatic Generation of Movie Audio Descriptions for visually impaired” (25 K€), 2015–2016.
- **Principal investigator** (at IRI-CSIC) of the ERA-Net Chistera project VISEN “Tagging visual data with semantic descriptions” (130 K€), 2013–2016.
- **Co-investigator** of the European project ARCAS “Aerial Robotics Cooperative Assembly System” (783 K€), 2012–2015.
- **Co-investigator** of the National project PAU + “Perception and Action under Uncertainty” (193 K€), 2012–2015.
- **Co-investigator** of the European project INTELLACT “Intelligent Observation and Execution of Actions and Manipulations” (367 K€), 2011–2014.
- **Co-investigator** of the European project GARNICS “Gardening with a Cognitive System” (477 K€), 2010–2013.
- **Co-investigator** of the National project PAU “Perception and Action under Uncertainty” (217 K€), 2009–2011.
- **Principal investigator** of the National project BPnP “Priors for Rigid and Non-Rigid Detection” (30 K€), 2009.
- **Co-investigator** of the National project MIPRCV “Multimodal Interaction in Pattern Recognition and Computer Vision (643 K€), 2008–2012.
- **Co-investigator** of the European project PACO + “Perception, Action and Cognition through Learning of Object-Action Complexes” (645 K€), 2006–2010.
- **Co-investigator** of the European project URUS “Ubiquitous Robotics in Urban Settings” (498 K€), 2006–2009.

- **Co-investigator** of the European project DYVINE “Dynamic Visual Networks” (211 K€), 2006–2008.

INDUSTRIAL COLLABORATIONS

Ongoing projects

- **Co-investigator** of the project “Termosold: Artificial Intelligent Techniques for Weld Inspections in Packaging Lines” with Volpak S.A.U. (75 K€), 2015-2017.

Finished project

- **Principal investigator** of the project “Semi-Automatic Neuronal Reconstruction in Cadmaid” with Howard Hughes Institute, Janelia Research Campus (61 K€), 2015–2016.
- **Principal investigator** of the project “Accurate Calibration Algorithms in Sport Events” with MediaPro (28 K€), 2014–2015.
- **Co-principal investigator** of the project “RecycLearn: Learning Computer Vision Strategies for Recycling Plants” with Sadako Technologies S.L. (6 K€), 2013–2014.
- **Co-principal investigator** of the project “Obstacle Avoidance for Aerial Robots with Computer Vision” with the Asociación de Industrias de Navarra (50 K€), 2010–2011.

INDUSTRIAL PhDs

Ongoing project

- **Principal investigator** of the AGAUR project “Geometric Computer Vision meets Deep Learning for Autonomous Driving Applications”, UPC-Ficosa, (21.6K€+ 3-year PhD support), 2016-2019.
- **Principal investigator** of the AGAUR project “Fashion Discovery: A Computer Vision Approachs”, UPC-Wide Eyes Technologies S.L, (21.6K€+ 3-year PhD support), 2016-2019.

OTHER FUNDING SOURCES

- **Nvidia Grant Program:** During the period 2015-2018, Nvidia has donated to our group up to 8 GPUs, with an approximate value of 12 K€.

SEMINARS, TUTORIALS AND INVITED TALKS

- “Deep Regression of Distance Matrices for 3D Human Pose Estimation and Action Recognition”, University of Bordeaux, France, 2017.
- “Distance Matrix Representations for 3D Human Pose Estimation and Action Recognition”, Ecole Polytechnique Fédérale de Lausanne, Switzerland, 2017.
- “Non-Rigid Shape from Single Images: From Linear to Deep Learning Formulations”. Xerox Research Center Europe, Grenoble, 2016.
- “3D Shape and Pose from Monocular Images”. Computer Vision Center, Universitat Autònoma de Barcelona, 2015.
- “Monocular 3D Detection of Rigid and Non-Rigid Objects”. Keynote speaker in Portuguese Conference on Pattern Recognition. Covilha, Portugal, 2014.
- “Monocular 3D Detection of Rigid and Non-Rigid Objects”. Jornadas de Automàtica. Valencia, Spain, 2014.

- “Algorithms for Non-Rigid Reconstruction and Recognition”. European Robotics Forum, Workshop on Dexterous Robotic Manipulation Systems for clothing and Flexible Materials. Rovereto, Italy, 2014.
- “Linear Formulations for Deformable Shape Reconstruction”. ISIT-CENTI (Faculté de Medicine), Université d’Auvergne Clermont Ferrand, France (Host by Prof. Adrien Bartoli), 2012.
- “Linear Formulations for Rigid and Non-Rigid 2D-to-3D Registration”. The 30th Pattern Recognition and Computer Vision Colloquium. Center for Machine Perception, Czech Technical University, Prague (Host by Prof. Jiri Matas), 2012.
- “Linear Formulations for Rigid and Non-Rigid 2D-to-3D Registration”. Information Technology and Telecommunication Department, Univ. Pompeu Fabra, Barcelona (Host by Prof. Xavier Binefa), 2012.
- “Closed Form Solutions to Rigid and Non-Rigid Detection”. Computer Vision Center, Universitat Autònoma de Barcelona, 2010.
- “Pose Estimation from known and unknown Point Correspondences”. Universidad Carlos III, Madrid, Spain (CEA Workshop on Computer Vision and Machine Learning), 2009.
- “Closed Form Solutions to Rigid and Non-Rigid 3D Surface Registration”. Institut de Robòtica i Informàtica Industrial, Barcelona, 2008.
- “Active Refocusing of Images and Videos”. Stony Brook University, New York, USA (Host by Prof. Dimitris Samaras), 2007.
- “Active Refocusing of Images and Videos”. Ecole Polytechnique Fédérale de Lausanne, Switzerland, 2007.
- “Helmholtz Stereopsis”. Ecole Polytechnique Fédérale de Lausanne, Switzerland, 2007.
- “Multiple-Cue Integration for Robust Tracking in Dynamic Environments”. Ecole Polytechnique Fédérale de Lausanne, Switzerland (Host by Prof. Pascal Fua), 2006.
- “Optimal Illumination for Image and Video Relighting”. Institut de Robòtica i Informàtica Industrial, Barcelona, 2005.
- “Fusion of a Multiple Hypotheses Color Model and Deformable Contours for Figure Ground Segmentation in Dynamic Environments”. Stony Brook University, New York, USA (Host by Prof. Dimitris Samaras), 2004.

VISITS

- ISIT-CENTI (Faculté de Medicine), Université d’Auvergne Clermont Ferrand, France (Host by Prof. Adrien Bartoli). September 2012 (2 weeks).

TEACHING EXPERIENCE

- Professor of the Master Course “Advanced Topics in Computer Vision”. Master’s degree in Automatic Control and Robotics, Universitat Politècnica de Catalunya, 2013-2017.
- Invited Speaker of the Master in Computer Vision Course “3D Vision”. Pompeu Fabra, 2015.
- Invited Speaker of the Master Course “Advanced Computer Vision”. Computer Vision Center, Universitat Autònoma de Barcelona, 2012.
- Invited Speaker of the Master Course “Advanced Computer Vision”. Computer Vision Center, Universitat Autònoma de Barcelona, 2011.
- Professor (in collaboration with V.Lepetit) of the Phd course “Selected Topics in Computer Vision”. Ecole Polytechnique Fédérale de Lausanne, Switzerland, 2007.
- Invited Speaker for the PhD Course “Advanced Topics in Computer Vision”, given by Prof. Shree Nayar. Columbia University, New York, USA, 2006.

STUDENTS SUPERVISION

Postdocs

1. Jordi Sanchez (2017 - present)
2. Lorenzo Porzi (2017), now at Mapillary.
3. Antonio Agudo (2016-2017), now Associate Researcher at IRI.
4. Arnau Ramisa (2015-2016), now at Wide Eyes.
5. Michael Villamizar (2012-2016), now at IDIAP.

Phd, ongoing

1. Javier Garcia (co-advised with A.Agudo), “Geometric Computer Vision meets Deep Learning for Autonomous Driving Applications”, 2016–present.
2. Albert Pumarola (co-advised with A.Sanfeliu), “Bridging the Gap between Geometry and Deep Learning”, 2016–present.
3. Ahmed Sabir (co-advised with L.Padró), “Text Recognition in the Wild”, 2016–present.
4. Alejandro Hernandez, “Instructing Robots using Natural Communications Skills”, 2016–present.
5. Victor Vaquero (co-advised with A.Sanfeliu), “Object Detection for Autonomous Driving using Deep Learning”, 2013–present.
6. Antonio Rubio (co-advised with E.Simo), “Using Computer Vision to Understand Fashion”, 2015–present.

Phd, finished

1. Adrián Peñate (co-advised with J.Andrade), “Robust Pose Estimation for UAVs”, 2017.
2. Edgar Simó (co-advised with C.Torras), “Understanding Human-Centric Images: From Geometry to Fashion”, 2015.
3. Eduard Trulls (co-advised with prof. A.Sanfeliu), “Enhancing low-level features with mid-level cues”, 2015.
4. Michael Villamizar (co-advised with Prof. A.Sanfeliu and J.Andrade), “Boosting Algorithms for Real Time Object Detection”, 2012.

Master’s thesis, finished

1. Mahed Nadar (coadvised with A.Hernandez), “CNN Benchmark in sewage pipe defects classification”, 2017.
2. Victor Blasco (co-advised with J.M.Porta), “Tracking Daphnia with Computer Vision”, 2017.
3. Sergi Molina (co-advised with A.Agudo), “Non-Rigid Structure from Motion for Complex Motion”, 2016.
4. Beñat Irastorza (co-advised with A.Agudo), “3D reconstruction of Deformable Objects with Volume”, 2016
5. Ferran Plana, “Sewer defects detection from depth images using deep learning”, 2016.
6. Ana Genova and Xavi Gironès (co-advised with A.Agudo), “Tree Recognition using Convolutional Neural Networks”, 2016.
7. Sinuhe Garré (co-advised with A.Penate), “Android Implementation of a 3D Pose Algorithm”, 2015.
8. Antonio Rubio (co-advised with M.Villamizar), “3D Pose Estimation using Convolutional Neural Networks”, 2015.
9. Edgar Riba (co-advised with A.Penate), “Implementation of a 3D Pose Estimation Algorithm”, 2015.

10. Fran Edwin Salgado, "Next Best View Algorithm based on DOF of a structured light 3D scanner", 2012.
11. Edgar Simó (co-advised with A.Pérez), "Kinematic Model of the Hand using Computer Vision", 2011.
12. Jordi Bautista (co-advised with J.Andrade), "Camera Motion and Time to Collision Estimation from Aerial Images", 2010.
13. Anna Tamarit, "Solving Correspondences for Non-Rigid Deformations", 2010.
14. Eduard Serradell, "Combining Geometric and Appearance Priors for Pose Recovery", 2010.

Other

1. Alexander Vakhitov, Visitor (2016), now at Moscow University.
2. Lluís Ferraz, Visitor (2013-2014), now at Catchoom.

PHD COMMITTEES

1. Lorenzo Porzi, advised by P.Valigi and E.Ricci, University of Perugia, Italy, 2017.
2. Yuxing Tang, advised by L.Chen and E. Dellandréa. Ecole Centrale de Lyon, France, 2016.
3. Carles Ventura, advised by X.Giró and V.Vilaplana. Universitat Politècnica de Catalunya, Barcelona, Spain, 2016.
4. Przemyslaw Glowacki, advised by P.Fua. Ecole Polytechnique Fédérale de Lausanne, Switzerland, 2016.
5. Agustin Ortega, advised by J.Andrade. Universitat Politècnica de Catalunya, Barcelona, Spain, 2015.
6. Jiaolong Xu, advised by Antonio Lopez. Computer Vision Center, Universitat Autònoma de Barcelona, Spain, 2015.
7. Marcel Alcoverro Vidal, advised by M.Pardas and J.R. Casas. Universitat Politècnica de Catalunya, Barcelona, Spain, 2014.
8. Antonio Rodríguez López, advised by P.E. López de Teruel and A.Ruiz. Universidad de Murcia, Spain, 2013.
9. Rafael Valencia, advised by J.Andrade. Universitat Politècnica de Catalunya, Spain, Barcelona, 2013.
10. Marco Pedersoli, advised by J.González and X.Roca. Computer Vision Center, Universitat Autònoma de Barcelona, Spain, 2012.
11. Nicolás Amezcuita, advised by F.Serratosa and R.Alquezar. Universitat Rovira i Virgili, Tarragona, Spain, 2009.
12. Pascal Lagger, advised by P.Fua. Ecole Polytechnique Fédérale de Lausanne, Switzerland, 2009.

EDITORIAL AND CONFERENCE DUTIES

Member of the organization committee

- Organization of the Jornadas Automática, Vigo, Spain. Chair of the Computer Vision Award, 2012.
- IEEE International Conference on Computer Vision (ICCV 2011), Barcelona. Local Area Chair and Demo Chair, 2011.
- Organization of the Jornadas Automática, Alicante, Spain. Chair of the Computer Vision Award, 2011.
- Organization of the Jornadas Automática, Jaén, Spain. Chair for the Computer Vision Award, 2010.
- Co-principal organizer of the Consolider Workshop on Vision and Robotics for Non-Interactive Decision Making, Barcelona, 2010.

- Organization of the Jornadas Automática, Valladolid, Spain. Chair for the Computer Vision Award.
- CEA Workshop on Machine Learning for Computer Vision, Madrid, Spain, 2009.
- Organization of the Iberoamerican Congress on Pattern Recognition (CIARP 2003), La Habana, 2003.
- Organization of the International Conference on Pattern Recognition (ICPR 2000), Barcelona, 2000.

Journal reviewer

- IEEE Transactions on Pattern Analysis and Machine Intelligence
- International Journal of Computer Vision
- IEEE Transactions on Image Processing
- Pattern Recognition
- ACM Transactions on Graphics
- Image and Vision Computing
- Computer Vision and Image Understanding
- IEEE Transactions on Instrumentation & Measurement
- Medical Image Analysis
- Journal of Mathematical Imaging and Vision
- International Journal of Pattern Recognition and Artificial Intelligence
- Machine Vision and Applications
- Journal of Robotics
- PLoS ONE

Area Chair

- International Conference on Pattern Recognition, ICPR 2018.
- British Machine Vision Conference, BMVC 2017.
- Asian Conference on Computer Vision, ACCV 2016.

Program committee member / Conference reviewer

- IEEE Conference on Computer Vision and Pattern Recognition, CVPR 2006–2008, 2011–2018.
- European Conference on Computer Vision, ECCV 2008, 2010, 2012, 2014, 2016, 2018.
- IEEE International Conference on Computer Vision, ICCV 2007, 2011, 2013, 2015, 2017.
- Neural Information Processing Systems, NIPS 2016, 2017.
- International Conference on Learning Representation, ICLR 2018.
- ACM Multimedia, 2016.
- British Machine Vision Conference, BMVC 2011.
- Asian Conference on Computer Vision, ACCV 2009, 2010.
- International Conference on 3D Vision, 3DV, 2015.
- IEEE International Conference on Advanced Video and Signal-Based Surveillance, AVSS, 2013.
- European Conference on Visual Media Production CVMP 2009, 2011.
- IEEE International Conference on Pattern Recognition, ICPR 2014, 2016.
- IEEE International Conference on Robotics and Automation, ICRA 2013–2017.
- IEEE International Conference on Intelligent Robots and Systems, IROS 2011–2017.
- International Conference on Robot and Human Interactive Communication, RO-MAN, 2018.

- International Conference on Advanced Robotics, ICAR, 2009.
- Eurographics 2006.
- CVPR Workshop on Human Pose, Motion, Activities and Shape in 3D, 2018.
- ECCV Workshop on Human Behavior Understanding: Towards Generating Realistic Visual Data of Human Behavior, 2018.
- Workshop on Vision and Language, VL, 2016.
- IEEE International Symposium on Mixed and Augmented Reality, ISMAR 2007.
- ECCV Workshop on Virtual/Augmented Reality for Visual Artificial Intelligence, 2016.
- ECCV Workshop on Consumer Depth Cameras for Computer Vision 2012.
- CVPR Workshop on Non-Rigid Shape Analysis and Deformable Image Alignment, NORDIA 2008, 2011.
- ICCV Workshop on Consumer Depth Cameras for Computer Vision 2011.
- ICCV Workshop on Dynamic Shape Capture and Analysis 2011.
- International Workshop on Mobile Multimedia Computing, MMC 2014, 2015.
- Conference of the Spanish Association on Artificial Intelligence, CAEPIA 2011.
- International Conference of the Catalan Association on Artificial Intelligence, CCIA 2011, 2012.

EVALUATION COMMITTEES

- Evaluator of INRIA Projects for the theme "Vision, perception and multimedia interpretation", France, 2018.
- Member of the evaluation committee of the H2020 Marie Skłodowska-Curie Actions programme, University of Leuven, 2016
- Member of the evaluation committee of P-Sphere, part of the H2020 Marie Skłodowska-Curie Actions programme, Universitat Autònoma de Barcelona, 2016.
- Project reviewer for the Austrian Science Fund (FWF), 2015.

OTHER

Administrative duties

- Department Head. Institut de Robòtica i Informàtica Industrial, CSIC-UPC, 2011-2014.
- Member of the Spanish Committee in Computer Vision, CEA, 2008-2012.

Press coverage

- Interview published in the magazine "Nyer", from Les Planes d'Hostoles, December 2017.
- "Neuroaesthetics in Fashion: Modeling the Perception of Fashionability", our CVPR 2015 paper appeared in several media, e.g.: New Scientist, Vogue, Huffington Post, Elle, Marie Claire, Yahoo Style.
- "Active Refocusing of Images and Videos", Computer Graphics World, Vol. 112, 2007
- "Active Refocusing of Images and Videos", Full Digital Innovation, Vol. 98, 2007.

PUBLICATIONS

Indicators of Quality in Scientific Production (Google Scholar, December 2017)

Total Publications	111
Citations	3038 (249/2013; 376/2014; 458/2015; 656/2016; 616/2017)
Citations 10 most cited papers	859, 275, 166, 113, 91, 75, 71, 69, 69, 56
H-Index	26
i10-index	50
1 Book Chapter (Springer) and 27 Journals (first quartile), among them:	
· 9 IEEE Trans. on Pattern Analysis and Machine Intelligence (Impact factor 2015: 6.077)	
· 4 International Journal of Computer Vision (Impact factor 2015: 4.278)	
· 3 Computer Vision and Image Understanding (Impact factor 2015: 2.134)	
· 2 Pattern Recognition (Impact factor 2015: 3.399)	
· 2 Image and Vision Computing (Impact factor 2015: 1.766)	
· 1 ACM Transactions on Graphics (Impact factor 2015: 4.218)	
28 highly selective conferences, with acceptance rates below 30%:	
· 15 IEEE Conference on Computer Vision and Pattern Recognition (CVPR)	
· 6 European Conference on Computer Vision (ECCV)	
· 5 IEEE International Conference on Computer Vision (ICCV)	
· 1 ACM Multimedia (ACM'MM)	
· 1 North American Chapter of the ACL (NAACL)	
48 international conferences, among them:	
· 8 IEEE International Conference on Robotics and Automation (ICRA)	
· 6 IEEE International Conference on Pattern Recognition (ICPR)	
· 5 British Machine Vision Conference (BMVC)	
· 3 IEEE International Conference on Intelligent Robots and Systems (IROS)	
· 2 Asian Conference on Computer Vision (ACCV)	
· 2 IEEE Winter Conference on Applications of Computer Vision (WACV)	

Book Chapters

1. E.Trulls, I.Kokkinos, A.Sanfeliu, F.Moreno-Noguer. Dense Segmentation-aware Descriptors. *Chapter in Dense Image Correspondences for Computer Vision, Eds. C. Liu and T. Hassner, Springer, 2015.*

Refereed Journals

2. A.Agudo, F.Moreno-Noguer. Robust Spatio-Temporal Clustering and Reconstruction of Multiple Deformable Bodies. To appear in *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 2018.
ISI Impact Factor 2015: 6.077.
3. A.Agudo, F.Moreno-Noguer. A Scalable, Efficient, and Accurate Solution to Non-Rigid Structure from Motion. *Computer Vision and Image Understanding (CVIU)*, 167(C), 121–133, February 2018.
ISI Impact Factor 2015: 2.134.
4. M.Villamizar, J.Andrade, A.Sanfeliu, F.Moreno-Noguer. Sequential Boosted Random Ferns for Object Detection. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 40(2), 272 - 288, February 2018.
ISI Impact Factor 2015: 6.077.
5. A.Agudo, F.Moreno-Noguer. Force-Based Representation for Non-Rigid Shape and Elastic Model Estimation. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 2017.
ISI Impact Factor 2015: 6.077.

6. A.Ramisa, F.Yan, F.Moreno-Noguer, K.Mikolajczyk. BreakingNews: Article Annotation by Image and Text Processing. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 40(5), 1072-185, June 2017.
ISI Impact Factor 2015: 6.077.
7. M.Villamizar, A.Garrell, A.Sanfeliu, F.Moreno-Noguer. Random Clustering Ferns for Multimodal Object Recognition. *Neurocomputing*, 28(9), 2445-2460, September 2017.
ISI Impact Factor 2015: 2.392.
8. L.Porzi, S.Rota, A.Peñate-Sánchez, E.Ricci, F.Moreno-Noguer. Learning Depth-aware Deep Representations for Robotic Perception. *IEEE Robotics and Automation Letters (RA-L)*, 2(2), 468–475, April 2017.
9. A.Garrell, M.Villamizar, F.Moreno-Noguer, A.Sanfeliu. Teaching Robot’s Proactive Behavior Using Human Assistance. *International Journal of Social Robotics (IJSR)*, 9(2), 231–249, April 2017.
ISI Impact Factor 2015: 1.198.
10. A.Agudo, F.Moreno-Noguer. Combining Local-Physical and Global-Statistical Models for Sequential Deformable Shape from Motion. *International Journal of Computer Vision (IJCV)*, 122(2), 371–387, April 2017.
ISI Impact Factor 2015: 4.278.
11. E.Simo-Serra, C.Torras, F.Moreno-Noguer. 3D Human Pose Tracking Priors using Geodesic Mixture Models. *International Journal of Computer Vision (IJCV)*, 122(2), 388–408, April 2017.
ISI Impact Factor 2015: 4.278.
12. J.Funke, J.Klein, F.Moreno-Noguer, A.Cardona, M.Cook. TED: A Tolerant Edit Distance for Segmentation Evaluation. *Methods*, 115, 119–127, February 2017.
ISI Impact Factor 2015: 2.377.
13. A.Agudo, F.Moreno-Noguer, B.Calvo, J.M.M.Montiel. Real-Time 3D Reconstruction of Non-Rigid Shapes with a Single Moving Camera. *Computer Vision and Image Understanding (CVIU)*, 153(C), 37–54, December 2016.
ISI Impact Factor 2015: 2.134.
14. A.Ramisa, G.Alenyà, F.Moreno-Noguer, C.Torras. A 3D descriptor to detect task-oriented grasping points in clothing. *Pattern Recognition (PR)*, 60, 936–948, December 2016.
ISI Impact Factor 2015: 3.399.
15. F.Moreno-Noguer, J.M.Porta. A Bayesian Approach to Simultaneously Recover Camera Pose and Non-Rigid Shape from Monocular Images. *Image and Vision Computing (IVC)*, 52, 141–153, August 2016.
ISI Impact Factor 2015: 1.766.
16. M.Villamizar, A.Garrell, A.Sanfeliu, F.Moreno-Noguer. Interactive Multiple Object Learning with Scanty Human Supervision. *Computer Vision and Image Understanding (CVIU)*, 149, 51–64, August 2016.
ISI Impact Factor 2015: 2.134.
17. A.Agudo, F.Moreno-Noguer, B.Calvo, J.M.M.Montiel. Sequential Non-Rigid Structure from Motion using Physical Priors. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 38(5), 979-994, May 2016.
ISI Impact Factor 2015: 6.077. Citations: 16.
18. G.Sanroma, A.Penate-Sanchez, R.Alquezar, F.Serratos, F.Moreno-Noguer, J.Andrade-Cetto, M.A. Gonzalez Ballester. MSCLique: Multiple Structure Discovery through Maximum Weighted Clique Problem. *PLoS ONE*, January 2016.
ISI Impact Factor 2015: 3.057.

19. E.Simo-Serra, C.Torras, F.Moreno-Noguer. DaLI: Deformation and Light Invariant Descriptor. *International Journal of Computer Vision (IJCV)*, 115(2), 136-154, 2015.
ISI Impact Factor 2015: 4.278. Citations: 15.
20. E.Serradell, M.A.Pinheiro, R.Sznitman, J.Kybic, F.Moreno-Noguer, P.Fua. Non-Rigid Graph Registration using Active Testing Search. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 37(3), 625-638, March 2015.
ISI Impact Factor 2015: 6.077. Citations: 11.
21. A.Ramisa, G.Alenya, F.Moreno-Noguer, C.Torras. Learning RGB-D Descriptors of Garment Parts for Informed Robot Grasping. *Engineering Applications of Artificial Intelligence (EAI)*, 35, 246-258, October 2014.
ISI Impact Factor 2014: 2.207. Citations: 11.
22. A.Penate-Sanchez, J.Andrade-Cetto, F.Moreno-Noguer. Exhaustive Linearization for Robust Camera Pose and Focal Length Estimation. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 35(10), 2387-2400, October 2013.
ISI Impact Factor 2013: 5.694. Citations: 29.
23. F.Moreno-Noguer, P.Fua. Stochastic Exploration of Ambiguities for Non-Rigid Shape Recovery. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 35(2), 463-475, February 2013.
ISI Impact Factor 2013: 5.694. Citations: 13.
24. M.Villamizar, J.Andrade-Cetto, A.Sanfeliu, F.Moreno-Noguer. Bootstrapping Boosted Random Ferns for Discriminative and Efficient Object Detection. *Pattern Recognition (PR)*, 45(9), 3141-3153, September 2012.
ISI Impact Factor 2012: 2.632. Citations: 32.
25. V.Lepetit, F.Moreno-Noguer, P.Fua. EPnP: An Accurate O(n) Solution to the PnP Problem. *International Journal of Computer Vision (IJCV)*, 81(2), 155-166, February 2009.
ISI Impact Factor 2008: 5.36. Citations: 742.
26. F.Moreno-Noguer, A.Sanfeliu, D.Samaras. Dependent Multiple Cue Integration for Robust Tracking. *IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)*, 30(4), 670-685, April 2008.
ISI Impact Factor 2008: 5.96. Citations: 75.
27. F.Moreno-Noguer, P.N.Belhumeur, S.K.Nayar. Active Refocusing of Images and Videos. *ACM Transactions on Graphics (SIGGRAPH)*, 26(3), 67-68, July 2007.
Acceptance rate (oral): 20.0%. ISI Impact Factor 2007: 3.41. Citations: 104.
28. F.Moreno-Noguer, A.Sanfeliu, D.Samaras. Integration of Deformable Contours and a Multiple Hypotheses Fisher Color Model for Robust Tracking in Varying Illuminant Environments. *Image and Vision Computing (IVC)*, 25(3), 285-296, March 2007.
ISI Impact Factor 2007: 1.03. Citations: 17.

Highly selective refereed conferences ¹

29. A.Pumarola, A.Agudo, A.Martinez, A.Sanfeliu, F.Moreno-Noguer. GANimation: Anatomically-aware Facial Animation from a Single Image (oral). *European Conference on Computer Vision (ECCV)*, Munich, Germany, September 2018.
Acceptance rate (oral): 2%.
30. A.Pumarola, A.Agudo, L.Porzi, A.Sanfeliu, V.Lepetit, F.Moreno-Noguer. Geometry-Aware Network for Non-Rigid Shape Prediction from a Single View. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Salt Lake City, USA, June 2018.
Acceptance rate: 29.6%.

¹Note: The top three computer vision conferences (ICCV, ECCV, CVPR) are highly competitive with low acceptance rates <30%. ICCV and ECCV have CiteSeer impact factor rankings in the top 5% and 7%, respectively of all computer science journals and conferences.

31. A.Pumarola, A.Agudo, A.Sanfeliu, F.Moreno-Noguer. Unsupervised Person Image Synthesis in Arbitrary Poses. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Salt Lake City, USA, June 2018.
Acceptance rate: 29.6%.
32. A.Agudo, F.Moreno-Noguer. Image Collection Pop-up: 3D Reconstruction and Clustering of Rigid and Non-Rigid Categories. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Salt Lake City, USA, June 2018.
Acceptance rate: 29.6%.
33. A.Hernández-Ruiz, L.Porzi, S.Rota-Bulo, F.Moreno-Noguer. 3D CNNs on Distance Matrices for Human Action Recognition. *ACM Multimedia (ACM'MM)*, Mountain View, USA, October 2017.
Acceptance rate (oral): 7.5%.
34. F.Moreno-Noguer. 3D Human Pose Estimation from a Single Image via Distance Matrix Regression. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Honolulu, USA, June 2017.
Acceptance rate (poster): 29.0%.
35. A.Agudo, F.Moreno-Noguer. DUST: Dual Union of Spatio-Temporal Subspaces for Monocular Multiple Object 3D Reconstruction. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Honolulu, USA, June 2017.
Acceptance rate (poster): 29.0%.
36. A.Vakhitov, J.Funke, F.Moreno-Noguer. Accurate and Linear Time Pose Estimation from Points and Lines (poster). *European Conference on Computer Vision (ECCV)*, Amsterdam, Netherlands, October 2016.
Acceptance rate (poster): 24.4%.
37. A.Quattoni, A.Ramisa, P.Swaroop Madhyastha, E.Simo-Serra, F.Moreno-Noguer. Structured Prediction with Output Embeddings for Semantic Image Annotation (poster) . *Conference of the North American Chapter of the Association for Computational Linguistics (NAACL)*, San Diego, USA, June, 2016.
38. A.Agudo, F.Moreno-Noguer. Learning Shape, Motion and Elastic Models in Force Space (poster). *International Conference on Computer Vision (ICCV)*, Santiago de Chile, December 2015.
Acceptance rate (poster): 25.0%. Citations: 10.
39. E.Simo, E.Trulls, L.Ferraz, I.Kokkinos, P.Fua, F.Moreno-Noguer. Discriminative Learning of Deep Convolutional Feature Point Descriptors (poster). *International Conference on Computer Vision (ICCV)*, Santiago de Chile, December 2015.
Acceptance rate (poster): 25.0%. Citations: 105.
40. A.Agudo, F.Moreno-Noguer. Simultaneous Pose and Non-rigid Shape with Particle Dynamics (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Boston, USA, June 2015.
Acceptance rate (poster): 25.0%. Citations: 18.
41. E.Simo-Serra, S.Fidler, F.Moreno-Noguer, R.Urtasun. Neuroaesthetics in Fashion: Modeling the Perception of Fashionability (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Boston, USA, June 2015.
Acceptance rate (poster): 25.0%. Citations: 31.
42. E.Trulls, S.Tsogkas, I.Kokkinos, A.Sanfeliu, F.Moreno-Noguer. Segmentation-aware Deformable Part Models (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Columbus, USA, June 2014.
Acceptance rate (poster): 29.0%. Citations: 22.
43. L.Ferraz, X.Binefa, F.Moreno-Noguer. Very Fast Solution to the PnP Problem with Algebraic Outlier Rejection (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Columbus, USA, June 2014.

Acceptance rate (poster): 29.0%. Citations: 39.

44. E.Trulls, I.Kokkinos, A.Sanfeliu, F.Moreno-Noguer. Dense Segmentation-aware Descriptors (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Portland, USA, June 2013. Acceptance rate (poster): 26.0%. Citations: 33.
45. E.Simo-Serra, A.Quattoni, C.Torras, F.Moreno-Noguer. A Joint Model for 2D and 3D Pose Estimation from a Single Image (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Portland, USA, June 2013. Acceptance rate (poster): 26.0%. Citations: 47.
46. E.Trulls, A.Sanfeliu, F.Moreno-Noguer. Spatiotemporal Descriptor for Wide-Baseline Reconstruction of Non-Rigid and Ambiguous Scenes (poster). *European Conference on Computer Vision (ECCV)*, Vol 7574 of Lecture Notes in Computer Science, pp.441-545, Florence, Italy, October 2012. Acceptance rate (poster): 25.0%. Citations: 16.
47. E.Serradell, P.Glowacki, J.Kybic, F.Moreno-Noguer, P.Fua. Robust Non-Rigid Registration of 2D and 3D Graphs (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Providence, USA, June 2012. Acceptance rate (poster): 24.1%. Citations: 21.
48. E.Simo-Serra, A.Ramisa, G.Alenya, C.Torras, F.Moreno-Noguer. Single Image 3D Human Pose Estimation from Noisy Observations (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Providence, USA, June 2012. Acceptance rate (poster): 24.1%. Citations: 63.
49. E.Serradell, A.Romero, R.Leta, C.Gatta, F.Moreno-Noguer. Simultaneous Correspondence and Non-Rigid 3D Reconstruction of the Coronary Tree from Single X-ray Images (poster). *International Conference on Computer Vision (ICCV)*, Barcelona, Spain, November 2011. Acceptance rate (poster): 24.0%. Citations: 25.
50. F.Moreno-Noguer. Deformation and Illumination Invariant Feature Point Descriptor (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Colorado Springs, USA, June 2011. Acceptance rate (poster): 22.7%. Citations: 40.
51. F.Moreno-Noguer, J.M.Porta. Probabilistic Simultaneous Pose and Non-Rigid Shape Recovery (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Colorado Springs, USA, June 2011. Acceptance rate (poster): 22.7%. Citations: 29.
52. F.Moreno-Noguer, J.M.Porta, P.Fua. Exploring Ambiguities for Monocular Non-Rigid Shape Estimation (poster). *European Conference on Computer Vision (ECCV)*, Vol 6313 of Lecture Notes in Computer Science, pp.361-374, Crete, Greece, September 2010. Acceptance rate (poster): 24.5%. Citations: 18.
53. E.Serradell, M.Özuysal, V.Lepetit, P.Fua, F.Moreno-Noguer. Combining Geometric and Appearance Priors for Robust Homography Estimation (poster). *European Conference on Computer Vision (ECCV)*, Crete, Vol 6313 of Lecture Notes in Computer Science, pp.58-72, Greece, September 2010. Acceptance rate (poster): 24.5%. Citations: 39.
54. J.Sanchez-Riera, J.Östlund, P.Fua, F.Moreno-Noguer. Simultaneous Pose, Correspondence and Non-Rigid Shape (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, San Francisco, USA, June 2010. Acceptance rate (poster): 22.3%. Citations: 36.
55. M.Villamizar, F.Moreno-Noguer, J.Andrade-Cetto, A.Sanfeliu. Efficient Rotation Invariant Object Detection using Boosted Random Ferns (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, San Francisco, USA, June 2010. Acceptance rate (poster): 22.3%. Citations: 53.

56. F.Moreno-Noguer, M.Salzmann, V.Lepetit, P.Fua. Capturing 3D Stretchable Surfaces from Single Images in Closed Form (poster). *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Miami, USA, pp.1842 - 1849, June 2009.
Acceptance rate (poster): 21.9%. Citations: 45.
57. F.Moreno-Noguer, V.Lepetit, P.Fua. Pose Priors for Simultaneously Solving Alignment and Correspondence (poster). *European Conference on Computer Vision (ECCV)*, Vol 5303 of Lecture Notes in Computer Science, pp.405-418, Marseille, France, September 2008.
Acceptance rate (poster): 23.3%. Citations: 66.
58. M.Salzmann, F.Moreno-Noguer, V.Lepetit, P.Fua. Closed-Form Solution to Non-Rigid 3D Surface Detection (poster). *European Conference on Computer Vision (ECCV)*, Vol 5303 of Lecture Notes in Computer Science, pp.581-594, Marseille, France, September 2008.
Acceptance rate (poster): 23.3%. Citations: 89.
59. F.Moreno-Noguer, V.Lepetit, P.Fua. Accurate Non-Iterative O(n) Solution to the PnP Problem (oral). *International Conference on Computer Vision (ICCV)*, pp.1-8, Rio de Janeiro, Brazil, October 2007.
Acceptance rate (oral): 3.9%. Citations: 258.
60. F.Moreno-Noguer, A.Sanfeliu, D.Samaras. Integration of Conditionally Dependent Object Features for Robust Figure/Background Segmentation (poster). *International Conference on Computer Vision (ICCV)*, pp.1713-1720, Beijing, China, October 2005.
Acceptance rate (poster): 15.5%. Citations: 12.

Other international conferences and workshops

61. A.Agudo, F.Moreno-Noguer. Deformable Motion 3D Reconstruction by Union of Regularized Subspaces. *IEEE International Conference on Image Processing (ICIP)*, Athens, Greece, October 2018.
62. V.Vaquero, A.Sanfeliu, F.Moreno-Noguer. Hallucinating Dense Optical Flow from Sparse Lidar for Autonomous Vehicles. *IEEE International Conference on Pattern Recognition (ICPR)*, Beijing, China, August 2018.
63. G.Rotger, F.Lumbreras, F.Moreno-Noguer, A.Agudo. 2D-to-3D Facial Expression Transfer. *IEEE International Conference on Pattern Recognition (ICPR)*, Beijing, China, August 2018.
64. V.Vaquero, A.Sanfeliu, F.Moreno-Noguer. Deep Lidar CNN to Understand the Dynamics of Moving Vehicles. *IEEE International Conference on Robotics and Automation (ICRA)*, Brisbane, Australia, May 2018.
Acceptance rate (oral): 40.6%.
65. I. del Pino, V.Vaquero, B.Maxini, J.Solà, F.Moreno-Noguer, A.Sanfeliu, J.Andrade-Cetto. Low resolution lidar-based multi-object tracking for driving applications (oral). *Robot 2017*, Seville, Spain, November 2017.
66. A.Rubio, L.Yu, E.Simo-Serra, F.Moreno-Noguer Multi-Modal Embedding for Main Product Detection in Fashion (oral). *International Conference on Computer Vision Workshops (ICCVW)*, Venice, Italy, October 2017.
Best Paper Award.
67. L.Porzi, A.Penate, E.Ricci, F.Moreno-Noguer. Depth-Aware Convolutional Neural Networks for Accurate 3D Pose Estimation in RGB-D Images. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, Canada, September 2017.
68. V.Vaquero, I. del Pino, F.Moreno-Noguer, J.Sola, A.Sanfeliu, J.Andrade-Cetto. Deconvolutional Networks for Point-Cloud Vehicle Detection and Tracking in Driving Scenarios. *European Conference on Mobile Robotics (ECMR)*, Paris, France, September 2017.
Acceptance rate (oral): 58%.

69. V.Vaquero, G.Ros, F.Moreno-Noguer, A.Lopez, A.Sanfeliu. Joint Coarse-and-Fine Reasoning for Deep Optical Flow. *IEEE International Conference on Image Processing (ICIP)*, Beijing, China, September 2017.
70. A.Rubio L.Yu, E.Simo-Serra, F.Moreno-Noguer. Multi-Modal Joint Embedding for Fashion Product Retrieval. *IEEE International Conference on Image Processing (ICIP)*, Beijing, China, September 2017.
71. A.Pumarola, A.Vakhitov, A.Agudo, A.Sanfeliu, F.Moreno-Noguer. Real-Time Monocular Visual SLAM with Points and Lines. *IEEE International Conference on Robotics and Automation (ICRA)*, Singapur, May 2017.
72. A.Rubio L.Yu, E.Simo-Serra, F.Moreno-Noguer. Multi-Modal Fashion Product Retrieval. *Workshop on Vision and Language*, Valencia, Spain, April 2017.
73. A.Ramisa, F.Yan, F.Moreno-Noguer, K.Mikolajczyk. The BreakingNews Dataset. *Workshop on Vision and Language*, Valencia, Spain, April 2017.
74. A.Agudo, F.Moreno-Noguer. Global Model with Local Interpretation for Dynamic Shape Reconstruction. *Winter Applications in Computer Vision (WACV)*, Santa Rosa, USA, February 2017.
75. A.Agudo, F.Moreno-Noguer. Recovering Pose and 3D Deformable Shape from Multi-Instance Image Ensembles (poster). *Asian Conference on Pattern Recognition (ACCV)*, Taipei, Taiwan, November 2016.
Acceptance rate (poster): 25%.
76. A.Rubio L.Yu, E.Simo-Serra, F.Moreno-Noguer. Boundary-aware Superpixel Segmentation (poster). *International Conference on Pattern Recognition (ICPR)*, Cancun, Mexico, December 2016.
77. J.Funke, J.Klein, F.Moreno-Noguer, A.Cardona, M.Cook. Structured Learning of Assignment Models of Neuron Reconstruction to Minimize Topological Errors (oral). *International Symposium on Biomedical Imaging (ISBI)*, Prague, Czech Republic, April 2016.
78. A.Agudo, J.M.M.Montiel, B.Calvo, F.Moreno-Noguer. Mode-Shape Interpretation: Re-Thinking Modal Space for Recovering Deformable Shapes (oral). *IEEE Winter Conference on Applications of Computer Vision (WACV)*, Lake Placid, USA, March 2016.
79. A.Penate-Sanchez, L.Porzi, F.Moreno-Noguer. Matchability Prediction for Full-Search Template Matching Algorithms (poster). *International Conference on 3D Vision (3DV)*, Lyon, France, October 2015.
Acceptance rate (poster): 39%.
80. A.Ramisa, J.Wang, Y.Lu, E.Dellandrea, F.Moreno-Noguer, R.Gaizauskas. Combining Geometric, Textual and Visual Features for Generating Prepositions in Image Descriptions (poster). *Conference on Empirical Methods in Natural Language Processing (EMNLP)*, Lisboa, Portugal, September 2015.
Acceptance rate (poster): 24.0%.
81. L.Ellebracht, A.Ramisa, P.Swaroop Madhyastha, J.Cordero-Rama, F.Moreno-Noguer, A.Quattoni. Semantic Tuples for Evaluation of Image to Sentence Generation (poster). *Vision and Language Workshop* (in EMNLP). Lisboa, Portugal, September 2015.
82. M.Villamizar, A.Garrell, A.Sanfeliu, F.Moreno-Noguer. Multimodal Object Classification using Random Clustering Trees (poster). *Iberian Conference on Pattern Recognition and Image Analysis (IBPRIA)*. Santiago de Compostela, Spain, June 2015.
Best Poster Award.
83. A.Rubio, M.Villamizar, L.Ferraz, A.Penate-Sanchez, A.Ramisa, E.Simo-Serra, A.Sanfeliu, F.Moreno-Noguer. Efficient Monocular Pose Estimation for Complex 3D Models (oral). *IEEE International Conference on Robotics and Automation (ICRA)*, Seattle, USA, May 2015.
Acceptance rate (oral): 41%.

84. M.Villamizar, A. Garrell, A.Sanfeliu, F.Moreno-Noguer. Modeling Robot's World with Minimal Effort (oral). *IEEE International Conference on Robotics and Automation (ICRA)*, Seattle, USA, May 2015. Acceptance rate (oral): 41%.
85. E.Simo-Serra, C.Torras, F.Moreno-Noguer. Lie Algebra-Based Kinematic Prior for 3D Human Pose Tracking (oral). *Machine Vision Applications (MVA)*, Tokyo, Japan, May 2015. **Best Paper Award.**
86. A.Penate, F.Moreno-Noguer, J.Andrade-Cetto, F.Fleuret. LETHA: Learning from High Quality Inputs for 3D Pose Estimation in Low Quality Images (oral). *International Conference on 3D Vision (3DV)*, Tokyo, Japan, November 2014.
87. E.Simo-Serra, S.Fidler, F.Moreno-Noguer, R.Urtasun. A High Performance CRF Model for Clothes Parsing (poster). *Asian Conference on Computer Vision (ACCV)*, Singapore, November 2014. Acceptance rate (poster): 27.0%. Citations: 28. Acceptance rate (oral): 17%.
88. L.Ferraz, X.Binefa, F.Moreno-Noguer. Leveraging Feature Uncertainty in the PnP Problem (poster). *British Machine Vision Conference (BMVC)*, Nottingham, UK, September 2014. Acceptance rate (poster): 30%.
89. E.Simo-Serra, C.Torras, F.Moreno-Noguer. Geodesic Finite Mixture Models (poster). *British Machine Vision Conference (BMVC)*, Nottingham, UK, September 2014. Acceptance rate (poster): 30%.
90. M.Villamizar, A.Sanfeliu, F.Moreno-Noguer. Fast Online Learning and Detection of Natural Landmarks for Autonomous Aerial Robots (oral). *IEEE International Conference on Robotics and Automation (ICRA)*, Hong Kong, China, May 2014. Acceptance rate (oral): 39%.
91. A.Amor-Martínez, A.Ruiz, F.Moreno-Noguer, A.Sanfeliu. On-board Real-time Pose Estimation for UAVs using Deformable Visual Contour Registration (oral). *IEEE International Conference on Robotics and Automation (ICRA)*, Hong Kong, China, May 2014. Acceptance rate (oral): 39%. Citations: 11.
92. A.Ramisa, G.Alenya, F.Moreno-Noguer, C.Torras. FINDDD: A Fast 3D Descriptor to Characterize Textiles for Robot Manipulation (oral). *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Tokyo, Japan, November 2013. Acceptance rate (oral): 43%. Citations:22.
93. A.Penate-Sanchez, J.Andrade-Cetto, F.Moreno-Noguer. Simultaneous Pose, Focal Length and 2D-to-3D Correspondences from Noisy Observations (poster). *British Machine Computer Vision (BMVC)*, Bristol, UK, September 2013. Acceptance rate (poster): 30%.
94. A.Garrell, M.Villamizar, F.Moreno-Noguer, A.Sanfeliu. Proactive Behavior of an Autonomous Mobile Robot for Human-Assisted Learning (oral). *International Symposium on Robot and Human Interactive Communication (RO-MAN)*, Gyeongju, Korea, August 2013. Citations: 13.
95. M.Pinheiro, R.Sznitman, E.Serradell, J.Kybic, F.Moreno-Noguer, P.Fua. Active Testing Search for Point Cloud Matching (oral). *Information Processing in Medical Imaging (IPMI)*, Asilomar, California, July 2013.
96. M.Villamizar, A.Garrell, A.Sanfeliu, F.Moreno-Noguer. Online Human-Assisted Learning using Random Ferns (oral). *International Conference on Pattern Recognition (ICPR)*, Tsukuba, Japan, November 2012. Acceptance rate (oral): 15%. Citations:15.
97. A.Ramisa, G.Alenya, F.Moreno-Noguer, C.Torras. Using Depth and Appearance Features for Informed Robot Grasping of Highly Wrinkled Clothes (oral). *IEEE International Conference on Robotics and*

- Automation (ICRA)*, Minnesota, USA, May 2012.
Acceptance rate (oral): 40%. Citations: 62.
98. G.Alenya, A.Ramisa, F.Moreno-Noguer, C.Torras. Characterization of Textile Grasping Experiments (oral). *Workshop on the Conditions for Replicable Experiments and Performance Comparison in Robotics Research* (in ICRA'12), Minnesota, USA, May 2012.
 99. E.Serradell, J.Kybic, F.Moreno-Noguer, P.Fua. Robust Elastic 2D/3D Geometric Graph Matching (oral). *SPIE Medical Imaging*, San Diego, USA, February 2012. Citations: 11.
 100. M.Villamizar, H.Grabner, J.Andrade-Cetto, A.Sanfeliu, L. Van Gool, F.Moreno-Noguer. Efficient 3D Object Detection using Multiple Pose-Specific Classifiers (oral). *British Machine Computer Vision (BMVC)*, Dundee, UK, September 2011.
Acceptance rate (oral): 8.0%. Citations: 18.
 101. E.Simo-Serra, F.Moreno-Noguer, A.Perez-Gracia. Design of Non-Anthropomorphic Robotic Hands for Anthropomorphic Tasks (oral). *International Design Engineering Technical Conferences (ASME)*, Washington DC, USA, August 2011.
 102. M.Villamizar, F.Moreno-Noguer, J.Andrade-Cetto, A.Sanfeliu. Detection Performance Evaluation of Boosted Random Ferns (oral). *Iberian Conference on Pattern Recognition and Image Analysis (IBPRIA)*. Vol 6669 of Lecture Notes in Computer Science, pp.67-75, Las Palmas, Spain, June 2011.
 103. M.Villamizar, F.Moreno-Noguer, J.Andrade-Cetto, A.Sanfeliu. Shared Random Ferns for Efficient Detection of Multiple Categories (poster). *International Conference on Pattern Recognition (ICPR)*, Istanbul, Turkey, August 2010.
Acceptance rate (poster): 35.6%. Citations: 18.
 104. A.Garrell, A.Sanfeliu, F.Moreno-Noguer. Discrete Time Motion Model for Guiding People in Urban Areas Using Multiple Robots (oral). *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Saint Louis, USA, pp.486-491, October 2009.
Best Paper Nomination. Acceptance rate (oral): 54%. Citations: 19.
 105. F.Moreno-Noguer, A.Sanfeliu, D.Samaras. A Target Dependent Colorspace for Robust Tracking (oral). *International Conference on Pattern Recognition (ICPR)*, pp.43-46, Hong Kong, China, August 2006.
Acceptance rate (oral): 14.0%.
 106. F.Moreno-Noguer, A.Sanfeliu, D.Samaras. Integration of Dependent Bayesian Filters for Robust Tracking (oral). *IEEE International Conference on Robotics and Automation (ICRA)*, pp.4081-4087, Orlando, USA, May 2006.
Acceptance rate (oral): 38.0%.
 107. F.Moreno-Noguer, S.K.Nayar, P.N.Belhumeur. Optimal Illumination for Image and Video Relighting (oral). *IEE European Conference on Visual Media Production (CVMP)*, pp.201-210, London, UK, December 2005.
Citations: 15.
 108. F.Moreno-Noguer, S.K.Nayar, P.N.Belhumeur. Optimal Illumination for Image and Video Relighting (Technical sketch, oral), *SIGGRAPH Sketch*, pp:1-2, Los Angeles, USA, August 2005.
Acceptance rate (oral): 25%.
 109. F.Moreno-Noguer, A.Sanfeliu. A Framework to Integrate Particle Filters for Robust Tracking in Non-stationary Environments (oral). *Iberian Conference on Pattern Recognition and Image Analysis (IBPRIA)*. Vol. 3522 of Lecture Notes in Computer Science, pp.93-101, Estoril, Portugal, June 2005.
Best Paper Award. ISI Impact Factor 2005: 0.402.
 110. F.Moreno-Noguer, A.Sanfeliu. Integration of Shape and a Multihypothesis Fisher Color Model for Figure-Ground Segmentation in Non-Stationary Environments (poster). *International Conference on*

Pattern Recognition (ICPR), pp.771-774, Cambridge, UK, August 2004.
Acceptance rate (poster): 35.1%.

111. F.Moreno-Noguer, A.Sanfeliu, D.Samaras. Fusion of a Multiple Hypotheses Color Model and Deformable Contours for Figure Ground Segmentation in Dynamic Environments (oral). *Workshop on Articulated and Non-Rigid Motion* (in CVPR'04), pp.1-13, Washington, USA, June 2004.
112. F. Moreno-Noguer, A. Sanfeliu. Adaptive color model for figure-ground segmentation in dynamic environments (oral). *Iberoamerican Congress on Pattern Recognition (CIARP)*. Vol. 3287 of Lecture Notes in Computer Science, pp.37-44, Puebla, Mexico, October 2004.
ISI Impact Factor (2004): 0.513.
113. F. Moreno-Noguer, J. Andrade-Cetto, A. Sanfeliu. Fusion of color and shape for object tracking under varying illumination (oral). *Iberian Conference on Pattern Recognition and Image Analysis (IBPRIA)*. Vol. 2652 of Lecture Notes in Computer Science, pp.580-588, Puerto de Andratx, Spain, June 2003.
ISI Impact Factor 2003: 0.514. Citations: 20.
114. F.Moreno-Noguer, A.Tarrida, J.Andrade-Cetto, A.Sanfeliu. 3D Real Time Head Tracking Fusing Color Histograms and Stereovision (poster). *International Conference on Pattern Recognition (ICPR)*, pp.368-371, Quebec, Canada, September 2002.
Acceptance rate (poster): 44.8%. Citations: 36.
115. F.Moreno-Noguer, J.Andrade-Cetto, A.Sanfeliu. Localization of Human Faces Fusing Color Segmentation and Depth from Stereo (oral). *IEEE International Conference on Emerging Technologies and Factory Automation (ETFA)*, pp.527-535, Antibes, France, June 2001.
Citations: 15.

National conferences

116. A.Sabir, F.Moreno-Noguer, L.Padró. Enhancing Text Spotting with a Language Model and Visual Context Information (oral). *21th International Conference of the Catalan Association of Artificial Intelligence*, Roses, Spain, October 2018.
117. J.Garcia, A.Agudo, F.Moreno-Noguer. Vehicle Pose Estimation using G-Net: Multi-Class Localization and Depth Estimation (poster). *21th International Conference of the Catalan Association of Artificial Intelligence*, Roses, Spain, October 2018.
118. A.Rubio, M.Villamizar, L.Ferraz, A.Penate-Sanchez, A.Sanfeliu, F.Moreno-Noguer. Efficient Monocular Pose Estimation using Complex 3D Models. *Jornadas de Automàtica*, Valencia, Spain, September 2014.
Best Computer Vision Paper Award.
119. G.Alenyà, F.Moreno-Noguer, A.Ramisa,C.Torras. Active Perception of Deformable Objects using 3D Cameras (oral). *Workshop in Robotics: Experimental Robotics*, Sevilla, Spain, November 2011.
120. A.Ramisa, G.Alenyà, F.Moreno-Noguer, C.Torras. Determining where to Grasp Cloth using Depth Information (oral). *14th International Conference of the Catalan Association of Artificial Intelligence*, Lleida, Spain, October 2011.
Citations: 13.
121. J.Scandalariis, R.Alqu  zar, J.Andrade-Cetto, J.Aranda, J.Climent, A.Grau, J.M.Mirats, F Moreno-Noguer, F.Serratososa, J.Verg  s, T.Vidal, A.Sanfeliu. Research at the learning and vision mobile robotics group 2004-2005 (poster), *Symposium on Pattern Recognition and Image Analysis, 1st Spanish Congress in Informatics*, Granada, Spain, September 2005.
122. J.Andrade-Cetto, A.Grau, J.Climent, F.Moreno-Noguer, R.Alqu  zar, F.Serratososa, J.Verg  s, T.Vidal, Y.Bolea, A.Sanfeliu. Research at the learning and vision mobile robotics group (oral), *Jornada de Recerca en Autom  tica, Visi   i Rob  tica, Recerca en Autom  tica, Visi   i Rob  tica*, pp. 117-128, Barcelona, Spain, February 2004.

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Miscellaneous

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