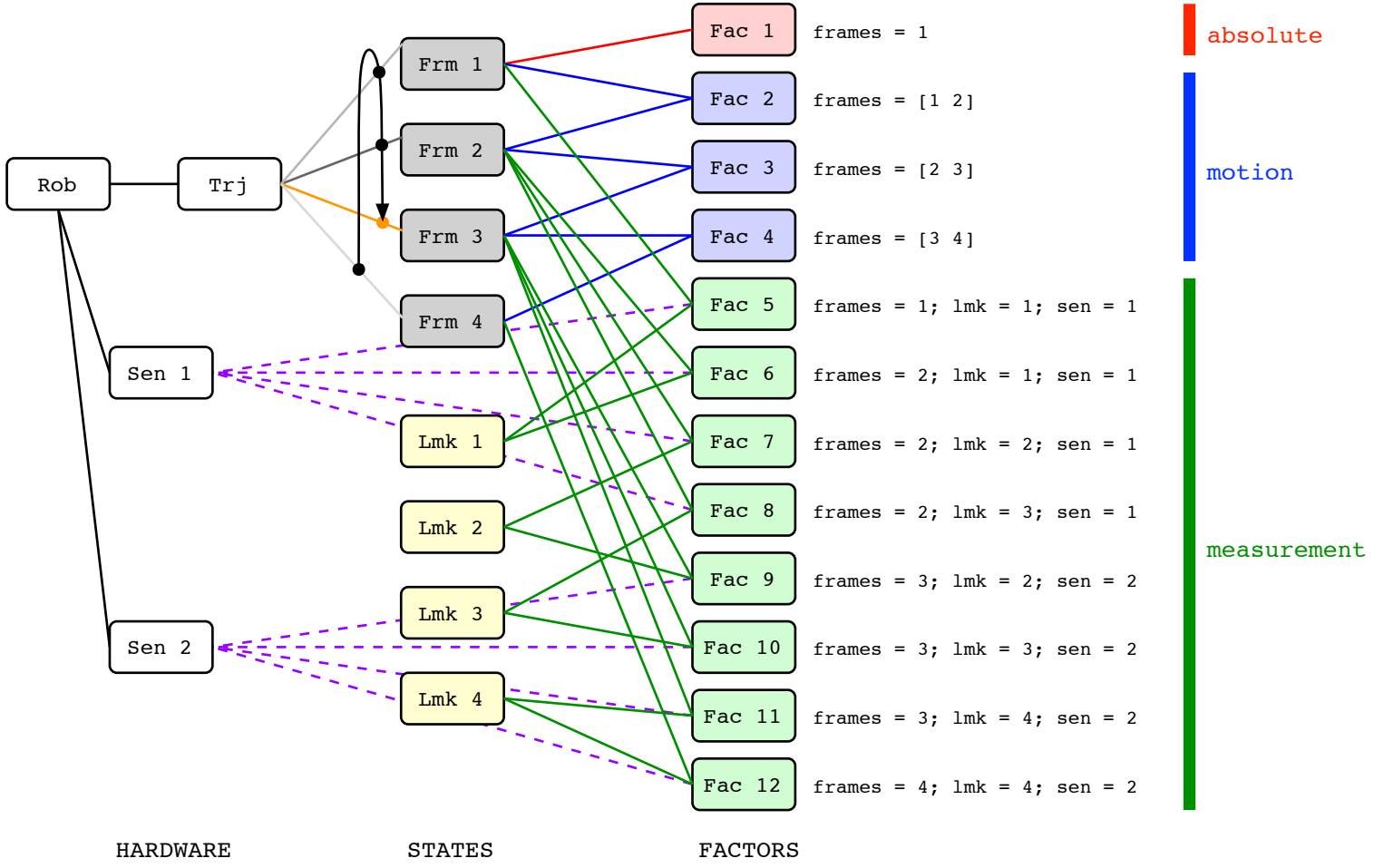
Rob
Trj
Sen 1
Sen 2
Frm 1
Frm 2
Frm 3
Frm 4
Lmk 1
Lmk 2
Lmk 3
Lmk 4
Fac 1
Fac 2
Fac 3
Fac 4
Fac 5
Fac 6
Fac 7
Fac 8
Fac 9
Fac 10
Fac 11
Fac 12
frames = 1
frames = [1 2]
frames = [2 3]
frames = [3 4]
frames = 1; lmk = 1; sen = 1
frames = 2; lmk = 1; sen = 1
frames = 2; lmk = 2; sen = 1
frames = 2; lmk = 3; sen = 1
frames = 3; lmk = 2; sen = 2
frames = 3; lmk = 3; sen = 2
frames = 3; lmk = 4; sen = 2
frames = 4; lmk = 4; sen = 2
absolute
motion
measurement
HARDWARE
STATES
FACTORS