### PROBLEM:
- Predicting motion hypothesis from poses
- Only generating feasible pose hypothesis

### CONTRIBUTIONS:
- Joint Pose and Kinematic Manifold
- Efficient approach for sampling
- Outperforms widely used Gaussian diffusion models

### KEY FEATURES:
- Generative Model
- Fully unsupervised
- Scales well to large datasets

### EXPERIMENTAL RESULTS
- Evaluation on Human3.6M dataset
- 15 categories of actions
- 6 actors used for training, 1 actor used for testing

### REFERENCES